

The Role of *Uncertainty* in Machine Learning

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Give me \$50,000 to invest for you..

I *predict* that GameStop stock will rise dramatically



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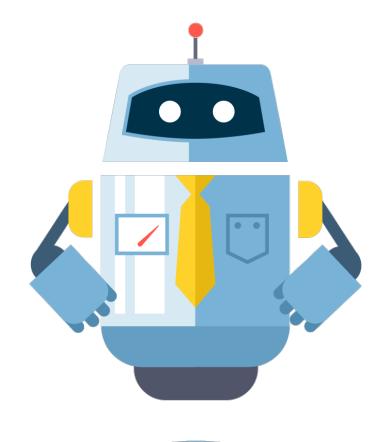




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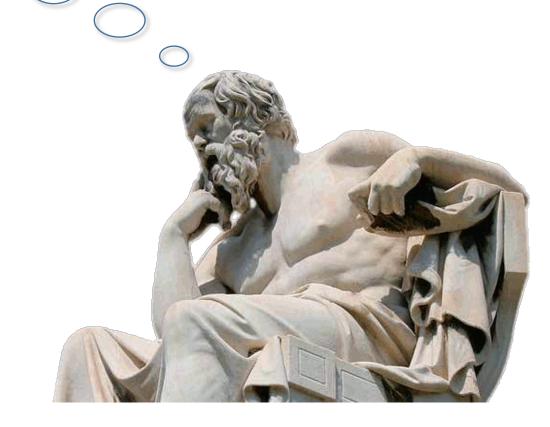




Motivation: what is uncertainty and how is it introduced in ML

What is uncertainty?

In general, uncertainty is lack of knowledge.



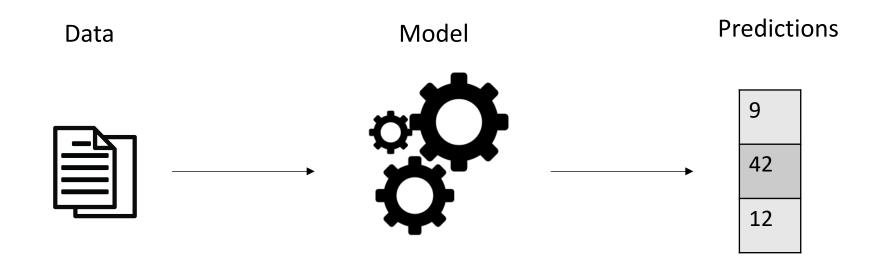
What is uncertainty?

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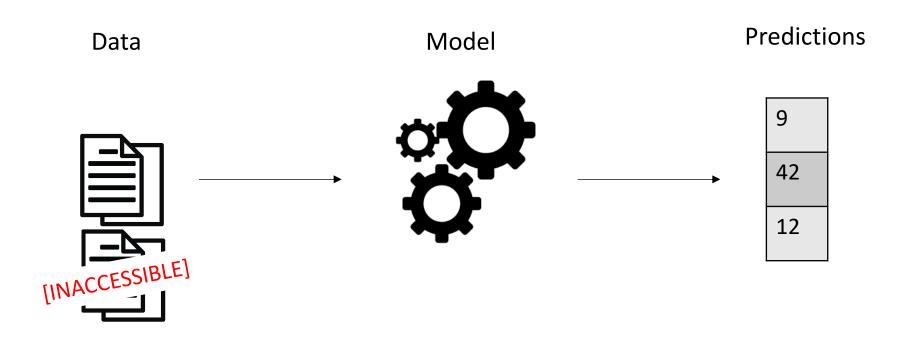
See: Neil's and Carl Henrik's talk!



(in theory)



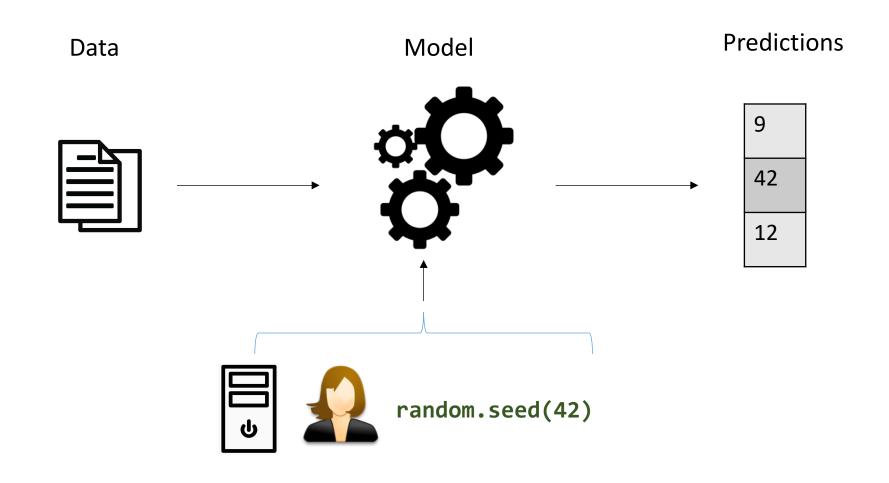
(in reality)



Our model only sees partial and noisy data.

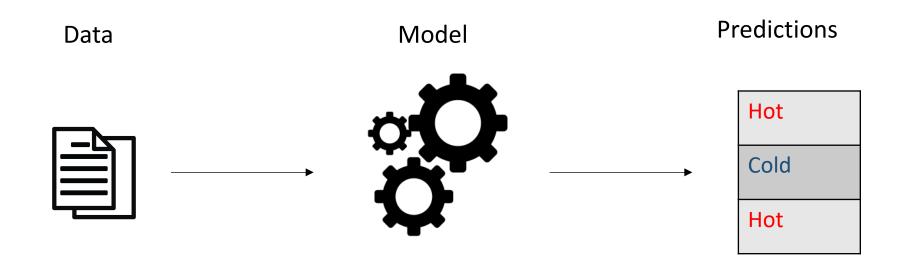


(in reality)



Our model is **imperfect**, possibly **biased** and often inherently **random**.

(in reality)



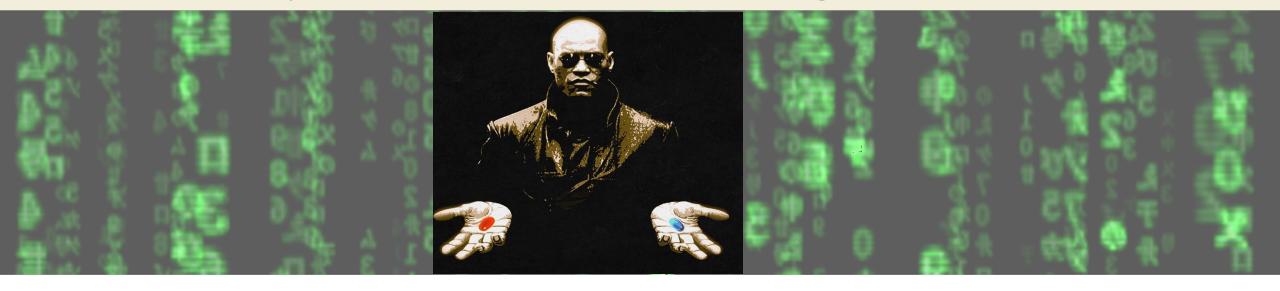
Interpretation of concepts can be **fuzzy**.

Computers are deterministic, but our world isn't

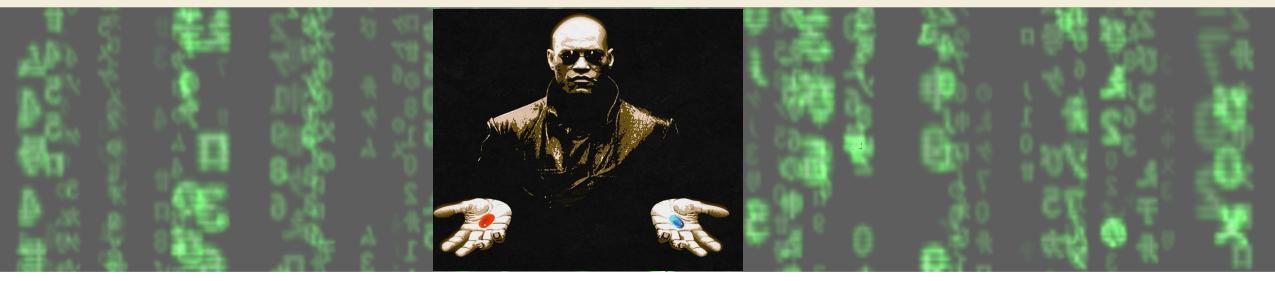
- Data, assumptions and model imperfections come from the real world. These induce uncertainty in our ML modeling
- Uncertainty is hidden in any modeling scenario whether we want it or not: we can never
 have complete knowledge (otherwise we wouldn't resort to modeling).
- Using uncertainty in our models is natural for humans: we plan our lives and actions
 using uncertainty and risk; we acknowledge we don't know everything

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Uncertainty is inevitable in modeling



Uncertainty is inevitable in modeling



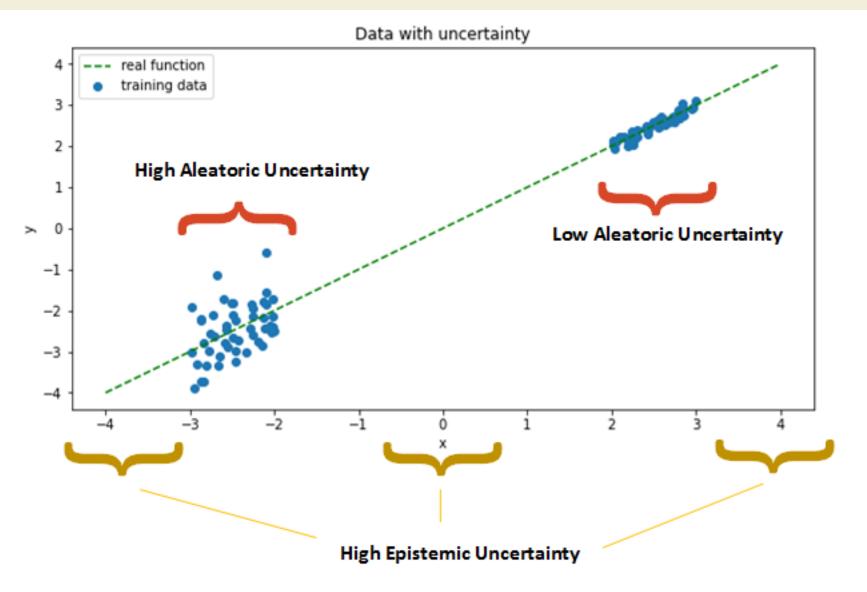
Epistemic uncertainty

Neo doesn't know that he lives in a simulation (Ignorance about the correct model that generated the data e.g. Matrix glitches)

Aleatoric uncertainty

Neo knows that he lives in a simulation but the simulation's complexity introduces *inherent* uncertainty (not enough capacity to perfectly observe the world)

Uncertainty is inevitable in modeling



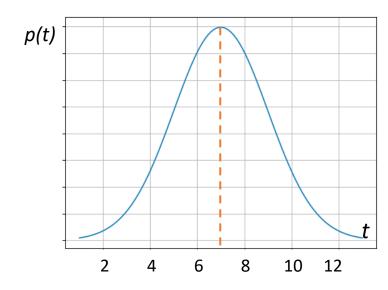
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Applications where uncertainty matters

Predictive uncertainty

► Classification: "I am 92% certain that this stock is a buy"

▶ **Regression**: *"The temperature tomorrow will follow \mathcal{N}(7,4)"*



Uncertainty in decision making

- Uncertainty can be used to guide decisions
- Same prediction can lead to different decisions depending on degree of confidence







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Sequential decision making

► Active Learning:

Select images to label such that expected accuracy is maximized



Bayesian Optimization:

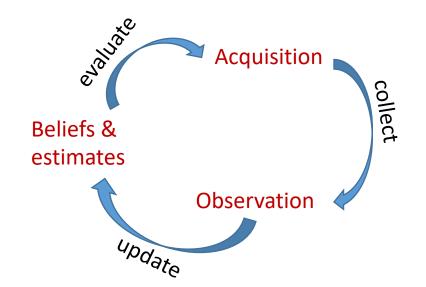
• Find the minimum of a function *f*



► Reinforcement Learning:

• Take *K* actions to collect maximum combined reward





Sequential decision making

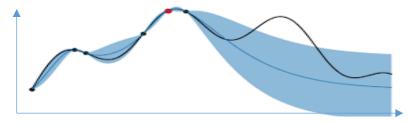
► Active Learning:

Select images to label such that expected accuracy is maximized



Bayesian Optimization:

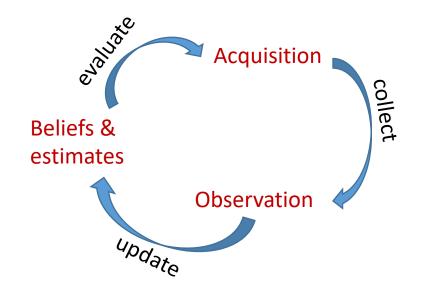
Find the minimum of a function f



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Sequential decision making

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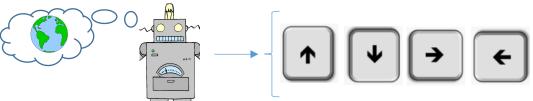
Bayesian Optimization:

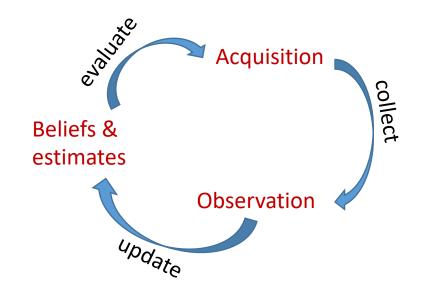
• Find the minimum of a function *f*



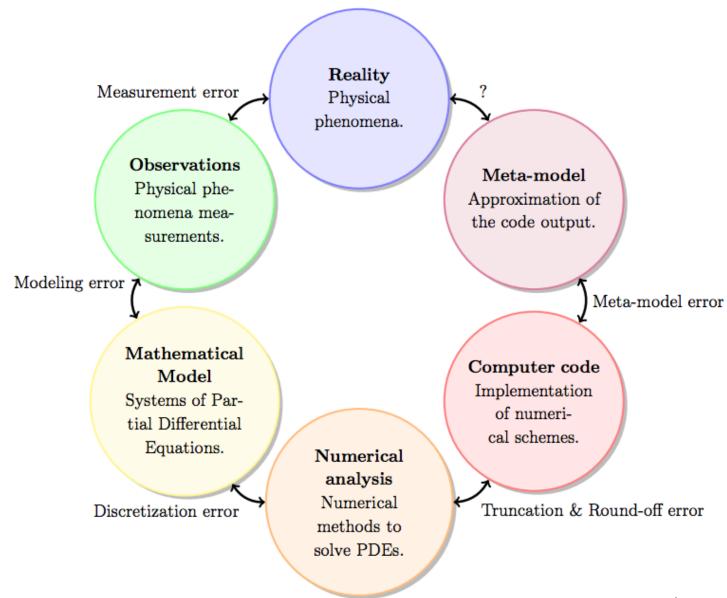
► Reinforcement Learning:

• Take K actions to collect maximum combined reward





Probabilistic numerics (aka uncertainty everywhere)



Quantifying and Auditing Uncertainty

Calibration

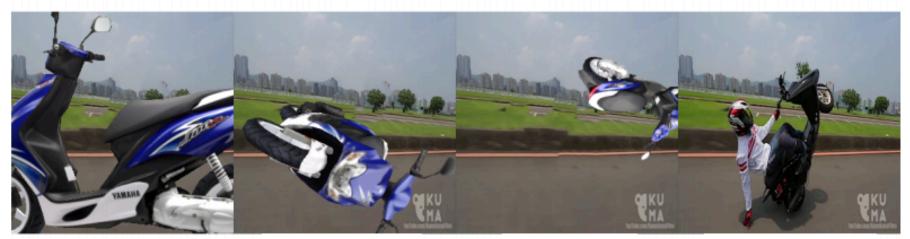
• We use uncertainty because we don't trust predictions (i.e. estimates of dependent variable).

• But why should we trust estimates of uncertainty?

Miscalibrated model predictions



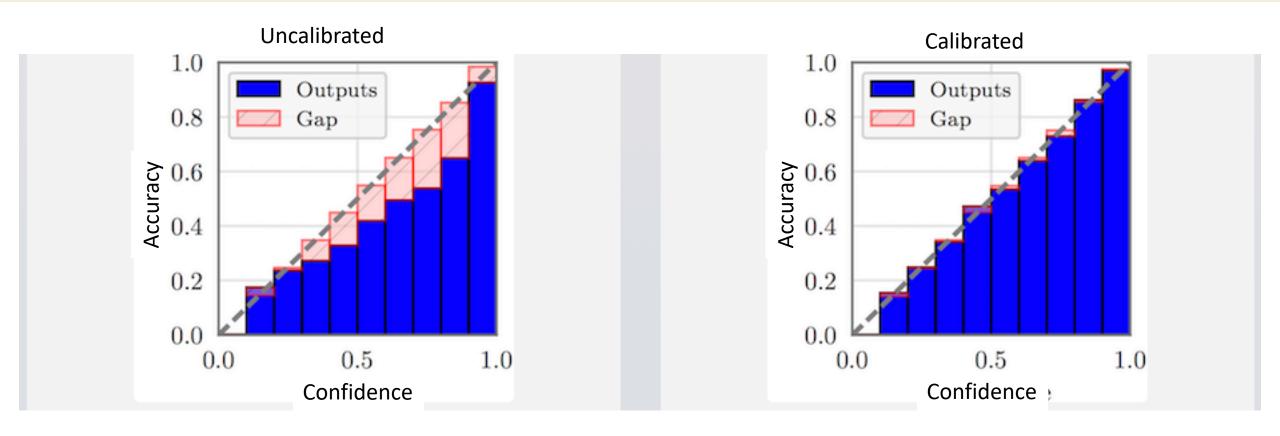
school bus 1.0 garbage truck 0.99 punching bag 1.0 snowplow 0.92



motor scooter 0.99 parachute 1.0

bobsled 1.0

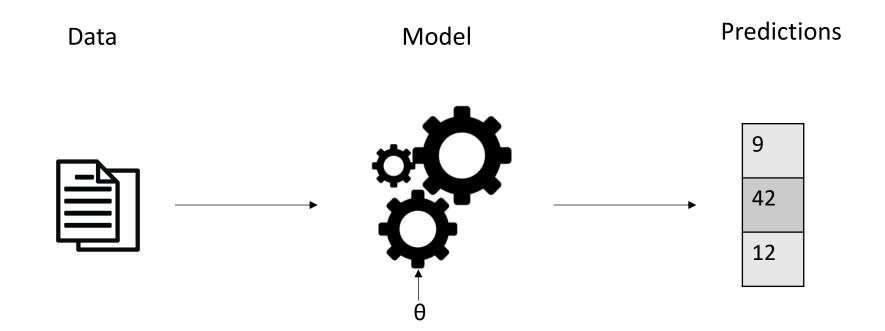
parachute 0.54

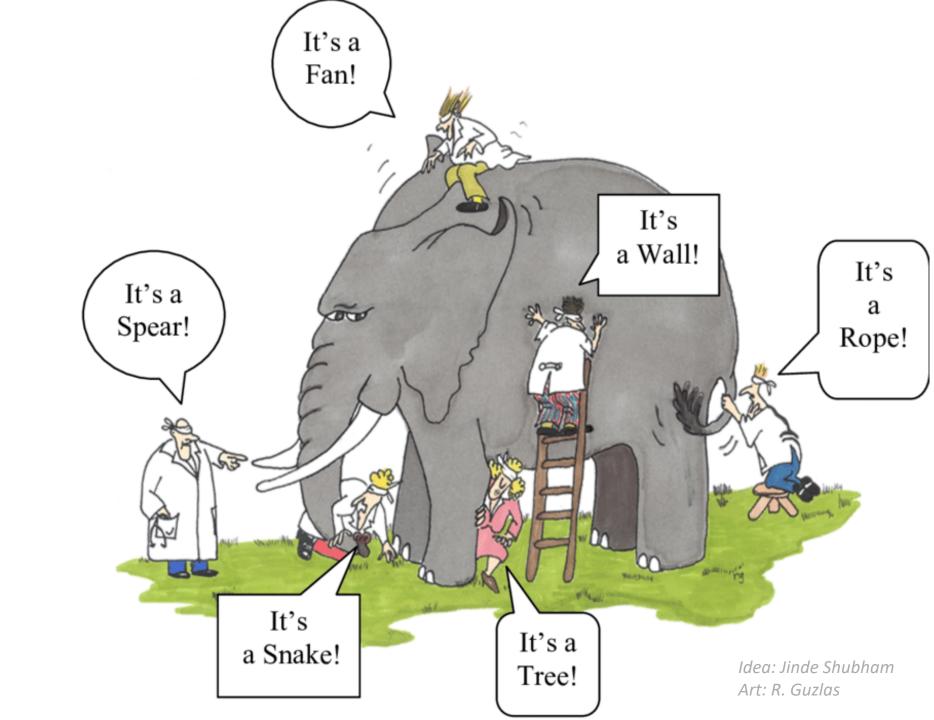


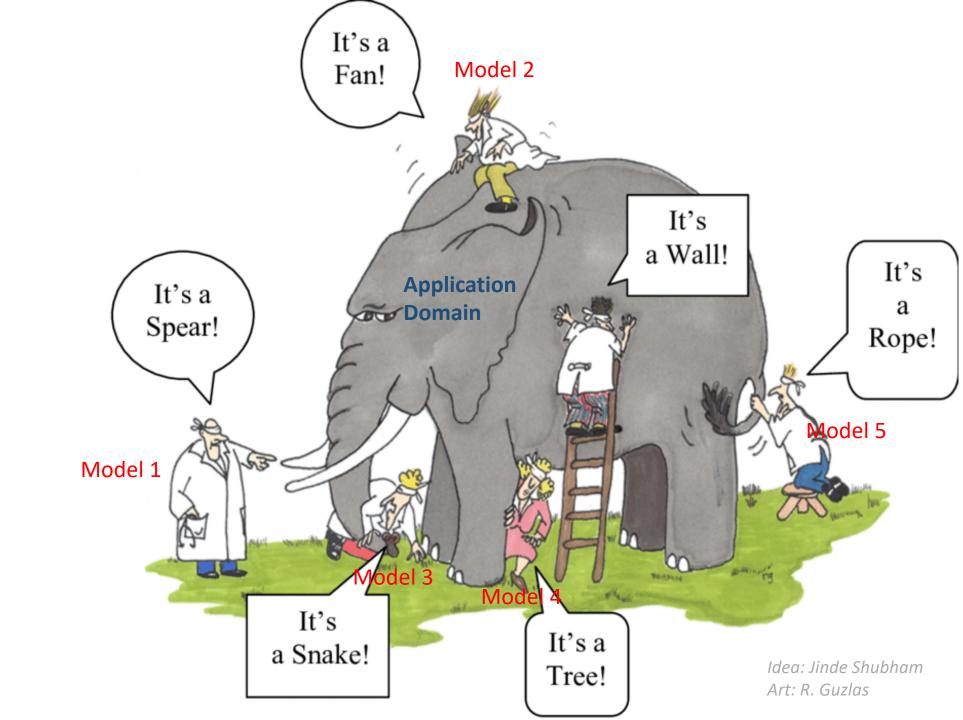
"If, for example, each of 100 predictions have confidence 80%, then we'd expect that 80% of those are actually correct. If this is the case, we say the model is **calibrated**."

Plot: Split predictions in bins. Then average accuracy and average confidence per bin should match.

Machine Learning modeling



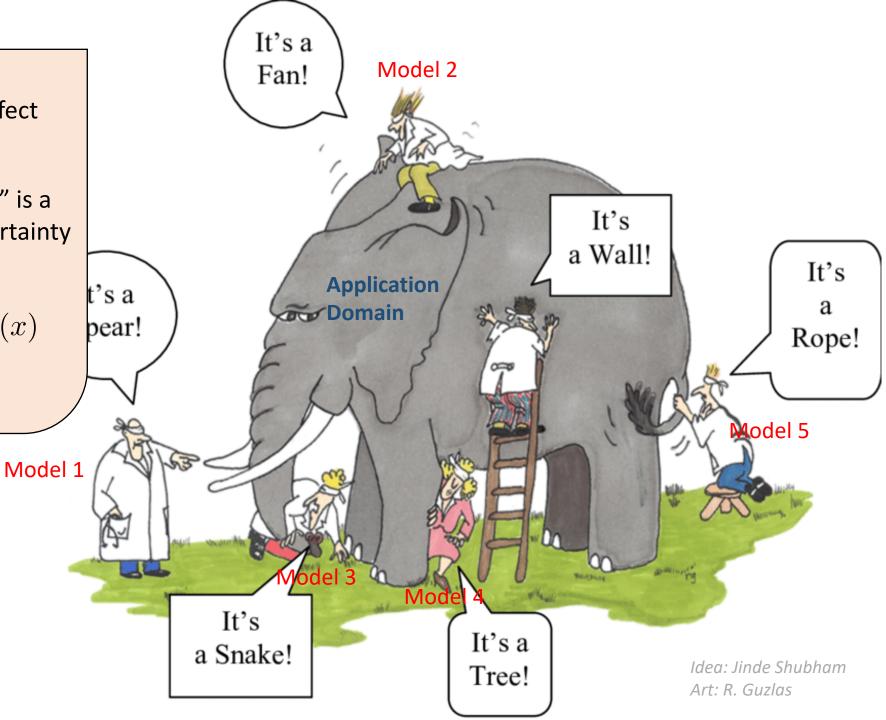




- Every trained model is imperfect
- Let's combine Models
- "Modeling the disagreement" is a crude way of improving uncertainty quantification

prediction =
$$\frac{1}{M} \sum_{m} p_{\theta_m}(x)$$

[Lakshminarayanan et al. 2017]



Bayesian model averaging

Model Combination:

$$p(x) = \frac{1}{M} \sum_{m} p_{\theta_m}(x)$$

(Bayesian)
Model Averaging:

$$p(x) = \int_{\theta} p_{\theta}(x) p(\theta|\text{data})$$

Well calibrated model uncertainty!

Bayes Rule:

$$p(\theta|\text{data}) = \frac{p(\text{data}|\theta)p(\theta)}{p(\text{data})}$$

Bayesian model averaging

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Given a test case, Bayesian modeling allows to *propagate* all uncertainties (data, prior, model...) into the final predictive distribution.

Bayes Rule:

$$p(\theta|\text{data}) = \frac{p(\text{data}|\theta)p(\theta)}{p(\text{data})}$$

(Bayesian) Linear Regression

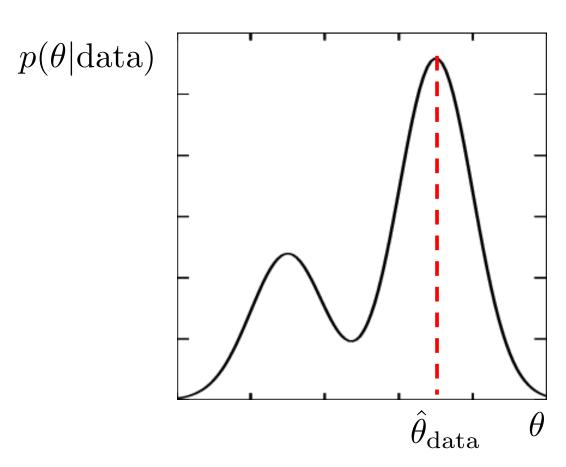
Error minimization formulation	Probabilistic formulation
$y = \theta^T x$	$p(y x;\theta) = \mathcal{N}(\theta^T x, \boldsymbol{\sigma}^2)$
$\hat{\theta} = \underset{\theta}{\operatorname{argmin}} \sum_{i} (y_i - \theta^T x_i)^2$	$\hat{\theta} = \underset{\theta}{\operatorname{argmax}} \ p(y x;\theta)$

Bayesian formulation

$$p(\theta|x,y) = \frac{p(x,y|\theta)p(\theta)}{p(x,y)}$$

Single point vs full posterior

Model Fitting

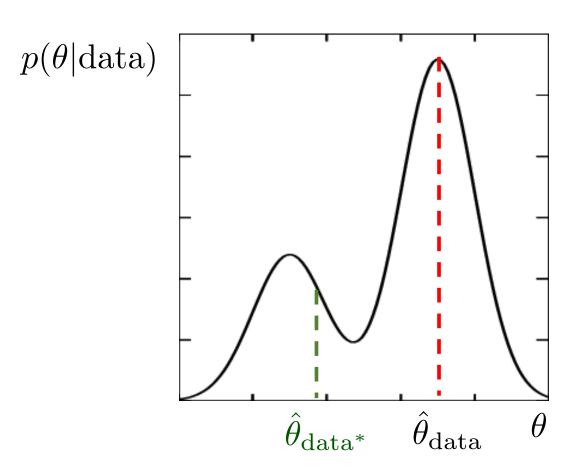


Predictions

$$p(x) = \int_{\theta} p_{\theta}(x) p(\theta|\text{data})$$

Single point vs full posterior

Model Fitting



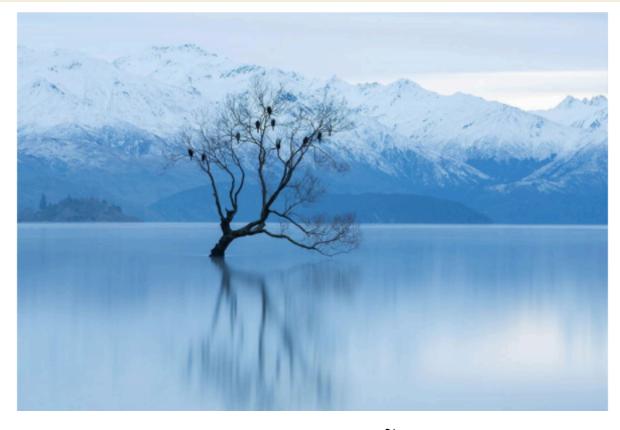
Predictions

$$p(x) = \int_{\theta} p_{\theta}(x) p(\theta|\text{data})$$

Out-of-sample data



 $y \sim p(Y; \theta)$

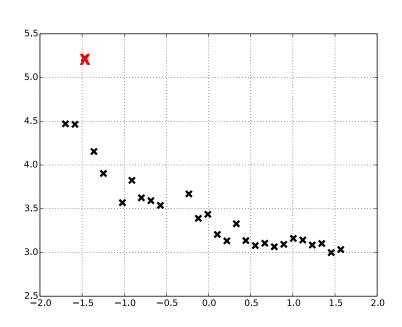


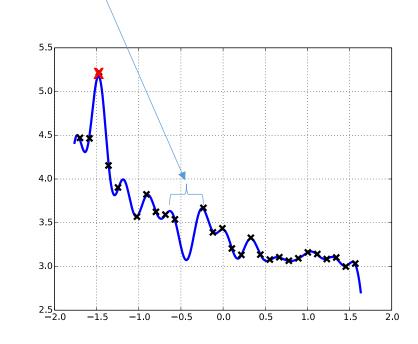
 $y \sim p(Y; \tilde{\theta})$

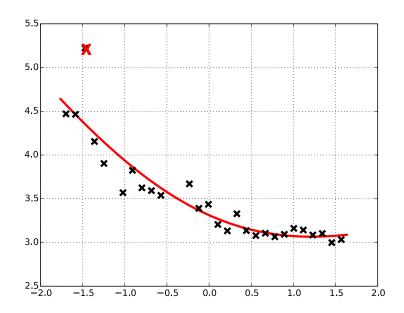
Generalization

▶ In a stretch, every point not in our training set can be thought of as out-of-sample.

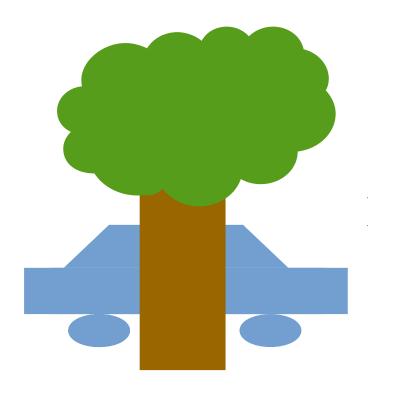
► Knowing what you don't know helps to not be over-confident. i.e *generalize* well Example: recognizing *epistemic uncertainty* helps being regularized







Occam's Razor

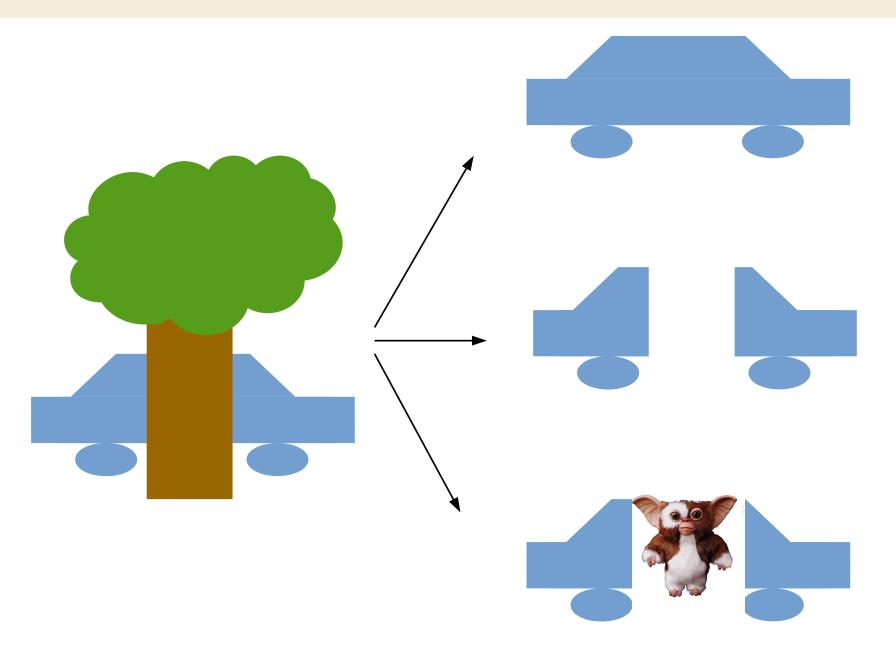


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Occam's Razor

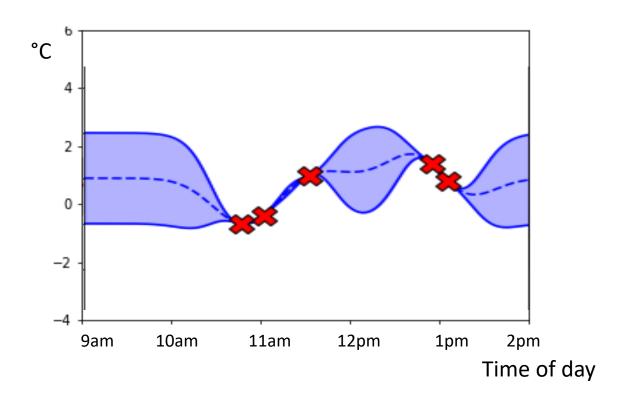
► Which inference is more *probable*?

► Which is *simpler*?



It's not magic: we combine data with assumptions

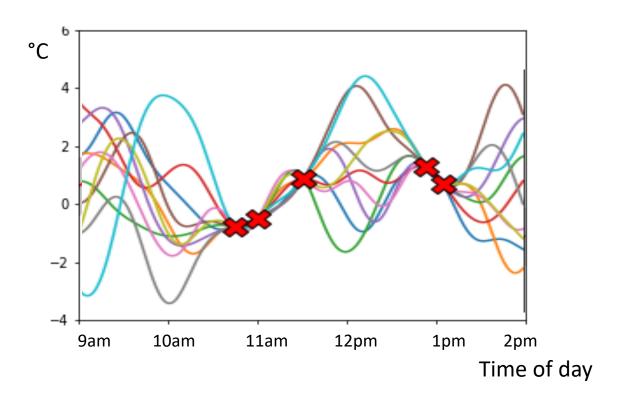
Uncertainty in Regression: Balancing *some notion* of simplicity, with *some notion* of smoothness & prior knowledge



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It's not magic: we combine data with assumptions

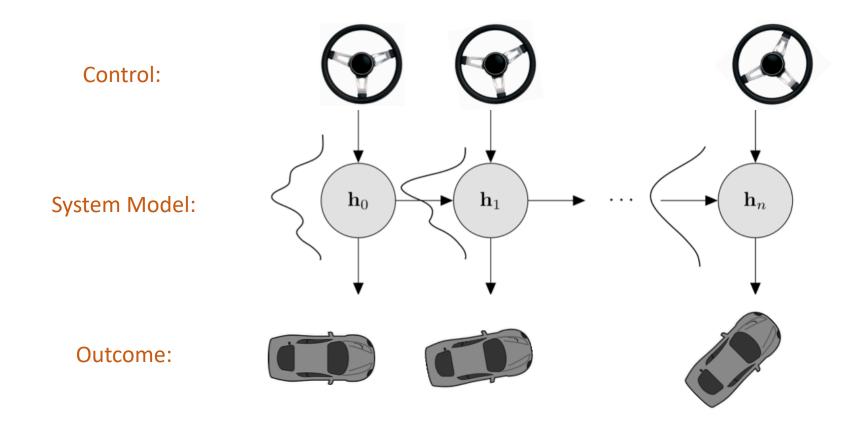
Uncertainty in Regression: Balancing *some notion* of simplicity, with *some notion* of smoothness & prior knowledge



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Propagation of uncertainty

Example: A ML model is trying to estimate the internal state of a car-system relying on noisy sensors.



Caveats

- Uncertainty modeling is computationally expensive
- Uncertainty propagation is even harder
- Approximations must often be used
- Calibration is not always guaranteed
- ► Mis-uses of uncertainty (e.g. mis-interpretations)

Thanks!

Questions?

Do you want to share your story?

Do you have an application where predictions alone aren't sufficient? ..or where uncertainty needs to be propagated across the scientific pipeline?